

Last Lecture Review

Recall a linear function $f: \mathbb{R}^n \rightarrow \mathbb{R}^p$

is a lin. satisfying

$$f(\vec{x} + \vec{y}) = f(\vec{x}) + f(\vec{y}) \quad \forall \vec{x}, \vec{y} \in \mathbb{R}^n$$

$$f(a\vec{x}) = af(\vec{x}) \quad a \in \mathbb{R}$$

There's a natural 1-1 correspondence

btw linear fns $\mathbb{R}^n \rightarrow \mathbb{R}^p$

and $p \times n$ matrices w/ real coefficients.

What is correspondence?

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{p1} & a_{p2} & \dots & a_{pn} \end{pmatrix} \text{ corresponds to } f$$

if any of the following equivalent conditions are true:

$$- f(\vec{e}_j) = (a_{1j}, a_{2j}, \dots, a_{pj}) \text{ for } j=1, \dots, n$$

- j th column of A is $f(\vec{e}_j)$ (viewed as a column vector)

- $f(x_1, x_2, \dots, x_n)$ has i th component

$$\sum_{j=1}^n a_{ij} x_j \quad i=1, \dots, p$$

If $\vec{f}_1, \vec{f}_2, \dots, \vec{f}_p$ denote component vectors in \mathbb{R}^p , then

$$\begin{aligned} f\left(\sum_{j=1}^n x_j \vec{e}_j\right) &= \sum_{j=1}^n \left(\sum_{i=1}^p a_{ij} x_j \vec{f}_i\right) \\ &= \sum_{i=1}^p \left[\sum_{j=1}^n a_{ij} x_j\right] \vec{f}_i \end{aligned}$$

$$f(x_1, \dots, x_n)$$

$$= A \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

Now what if we compose fns?

Say

$$F: \mathbb{R}^n \rightarrow \mathbb{R}^p$$

$$g: \mathbb{R}^p \rightarrow \mathbb{R}^q$$

$$g \circ F: \mathbb{R}^n \rightarrow \mathbb{R}^q$$

sends $x \in \mathbb{R}^n$ to $g(F(x)) \in \mathbb{R}^q$

Fact 1 If F and g are linear, then so is $g \circ F$

$$\begin{aligned} \text{e.g. } g(F(\vec{x} + \vec{y})) &= g(F(\vec{x}) + F(\vec{y})) \\ &= g(F(\vec{x})) + g(F(\vec{y})) \end{aligned}$$

Say F corresponds to matrix A ($p \times n$ matrix) and g corresponds to B ($q \times p$ matrix)

Q/ Then which $q \times n$ matrix corresponds to $g \circ F$?

A/ Matrix product BA

Suppose C corresponds to $g \circ F$. Then, its j th column is $g(F(\vec{e}_j))$

Q/ What is $g(F(\vec{e}_j))$ in terms of A & B ?

$$\begin{aligned} g(F(\vec{e}_j)) &= g(\text{jth column of } A) \\ &= g(a_{1j}, a_{2j}, \dots, a_{pj}) \end{aligned}$$

a vector of length q

its i th component is $\sum_{k=1}^p b_{ik} a_{kj}$

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so this is the ij component/coefficient of C (def'd as the matrix representing $g \circ f$)

$$C = BA$$

This is matrix multiplication on

→ C is the matrix w/ columns $Bf(Ce_j)$

⇒ $\text{col}(C)$ correspond to $\text{col}(A)$

⇒ $\text{row}(C)$ correspond to $\text{row}(B)$

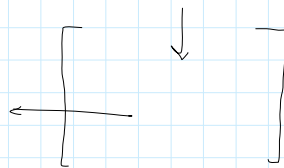
⇒ $\text{col}(B)$ & $\text{row}(A)$ just get jumbled around

Thinking in terms of input/output:

$\text{col}(A)$ correspond to components of input of F and

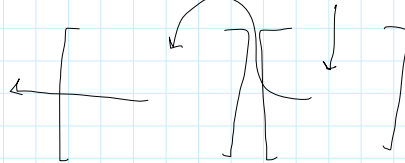
rows of A correspond to components of the output of F

(similar for B and g)



in through the columns,
out through the rows

Matrix mult



Limits & Interior

Open ball

$$B(\vec{a}; r) = \left\{ \vec{x} \in \mathbb{R}^n \mid \|\vec{x} - \vec{a}\| < r \right\}$$

Closed ball

$$\bar{B}(\vec{a}; r) = \left\{ \vec{x} \in \mathbb{R}^n \mid \|\vec{x} - \vec{a}\| \leq r \right\}$$

Let D be a subset of \mathbb{R}^n . We say that $\vec{x} \in D$ is an interior of D if

intuitively: if \vec{y} is near \vec{x} , then $\vec{y} \in D$

formally: $\exists \delta > 0$ s.t. $B(\vec{x}; \delta) \subseteq D$

We say D is open if every point of D is an interior point i.e. an "open subset of \mathbb{R}^n "

Examples

- open interval for $n=1$
- union of open intervals ($n=1$)

- union of n -open intervals $(n-1)$
- all of \mathbb{R}^n
- \emptyset the empty set
- open ball $B(a; r)$ (any n) ← inside of a circle
- $n=2$: interior of a square / any polygon
- $n=2$: set of (x, y) satisfying a strict linear inequality like:
 - $x > 0$
 - $x > -7$
 - $y < 3$
 - $x + y < 4$
 - $ax + by < c$less than, rather than less than or equal to
- same for linear inequalities for any n

Usually we prefer to consider a fcn def'd on an open domain.

Why?

- IF F def'd at \vec{x} , then F is def'd near \vec{x} and therefore, we can talk about $\lim_{\vec{y} \rightarrow \vec{x}}$ and F will be def'd at \vec{y} near \vec{x}
- Another way to state def'n of open set: D is open if whenever $\vec{x} \in D$, then all points sufficiently close to \vec{x} are also in D .

Nonexample

- $D = \text{a point}$ not open
- and indeed if F is def'd at only a single point, we can't talk about derivatives or limits at that point.

Other non-open sets

- a line in \mathbb{R}^2 (or \mathbb{R}^3 , etc)
- a plane in \mathbb{R}^3
- closed ball $\overline{B}(a; r)$ $r \geq 0$
- closed interval
- half-open interval
- square (incl. the boundary) in \mathbb{R}^2
- an open square along with a single point on the boundary

Another intuitive def of open

- a set is open if it has no boundary points

Derivatives in Multiple Dimensions

Idea, derivative of a fcn $F: D \rightarrow \mathbb{R}$ with $D \subseteq \mathbb{R}^n$ (open) at a point $x_0 \in D$ is a number $F'(x_0)$

We should think of it as a 1×1 matrix, i.e., as a linear fcn from \mathbb{R}^1 to \mathbb{R}^1 that approximates F near (x_0, y_0) $y_0 = F(x_0)$

Technical Note. IF L is linear, then $L(0) = 0$,

so if we want to translate L to the point (x_0, y_0) , we really consider the affine fcn $y = L(x - x_0) + y_0 = L(x) + y_0 - L(x_0)$

So when we say L approximates F near (x_0, y_0) we really mean $L(x - x_0) + y_0$ approximates F .

(\Rightarrow) L itself approximates $F(x + x_0) - y_0$

This applies to $x_0 \in \mathbb{R}^n$, $y_0 \in \mathbb{R}^p$ and $L: \mathbb{R}^n \rightarrow \mathbb{R}^p$
i.e., if we translate L to (x_0, y_0) , we take $L(\vec{x} - \vec{x}_0) + \vec{y}_0$.

Suppose $F: D \rightarrow \mathbb{R}^p$ where D is an open subset of \mathbb{R}^n

For $\vec{x}_0 \in D$, we want to define what we mean by $F'(\vec{x}_0)$.
 It will be a linear fcn from \mathbb{R}^n to \mathbb{R}^p .

s.t.

$$\underbrace{f'(\vec{x}_0)}_{\substack{\text{linear} \\ \text{fcn}}} \underbrace{(\vec{x} - \vec{x}_0)}_{\substack{\text{input to} \\ \text{linear} \\ \text{fcn}}} + F(\vec{x}_0)$$

is the best affine approximation to F near \vec{x}_0

More precisely we define "best" and what it means for F to be differentiable

F is differentiable at \vec{x}_0 iff $F'(\vec{x}_0)$ exists

Even more precisely

Recall precise def for $n=p=1$

Attempt to generalize to arbitrary p, n

$$F'(\vec{x}_0) = \lim_{\vec{x} \rightarrow \vec{x}_0} \frac{F(\vec{x}) - F(\vec{x}_0)}{\vec{x} - \vec{x}_0}$$

PROBLEM

can't divide vectors by other vectors

Instead, the gap def will be:

$$F(\vec{x}) - F(\vec{x}_0) \approx F'(\vec{x}_0)(\vec{x} - \vec{x}_0)$$

for \vec{x} near \vec{x}_0

Q/ what do we mean precisely by " \approx "?

At a look $\frac{d}{dx} \frac{F(x) - F(x_0)}{x - x_0}$

Notice that the x eq of $F'(x_0) = \lim_{x \rightarrow x_0} \frac{F(x) - F(x_0)}{x - x_0}$

is equivalent to

$$0 = \lim_{x \rightarrow x_0} \frac{F(x) - F(x_0)}{x - x_0} - F'(x_0)$$

$$= \lim_{x \rightarrow x_0} \frac{F(x) - F(x_0) - F'(x_0)(x - x_0)}{x - x_0}$$

Key Fact

a limit approaches 0 iff its magnitude approaches 0.

So, def of derivative is equivalent to:

$$0 = \lim_{x \rightarrow x_0} \left| \frac{F(x) - F(x_0) - F'(x_0)(x - x_0)}{x - x_0} \right|$$

$$= \lim_{x \rightarrow x_0} \frac{|F(x) - F(x_0) - F'(x_0)(x - x_0)|}{|x - x_0|}$$

So F is differentiable at x_0 iff $\lim_{x \rightarrow x_0} \frac{|F(x) - F(x_0) - F'(x_0)(x - x_0)|}{|x - x_0|} = 0$

$$\frac{1}{|x - x_0|}$$

So if we replace x, x_0 with \vec{x}, \vec{x}_0 , then we get.

$$0 = \lim_{\vec{x} \rightarrow \vec{x}_0} \frac{\|F(\vec{x}) - F(\vec{x}_0) - F'(\vec{x}_0)(\vec{x} - \vec{x}_0)\|}{\|\vec{x} - \vec{x}_0\|}$$

No more division by vectors \square

use this as def of $F'(\vec{x}_0)$